

**OSAKABE**

Profile	Physical description
<p><b>Name:</b> Oshichiya</p> <p><b>Species:</b> Humanoïd - 100% / total</p> <p><b>Occupation:</b> She's not seen much, said to only leave her chambers once a year. No one quite knows what goes on behind the doors the rest of the year, she isn't actually the social type.</p>	<p><b>Slim with Hunchback Posture</b></p> <ul style="list-style-type: none"> <li><b>Face:</b> She wears a mask, not many know what's underneath.</li> <li><b>Height:</b> 5'9", but her 12 layered Kimono makes her seem a lot bigger!</li> </ul>
<p><b>Gameplay</b></p> <p><b>DONT LOOK!</b></p> <p>She may be shy and dangerous aura seem like something you want to keep an eye on. Also, that urge, it'd be the last thing you'll ever see!</p> <p><b>Her Lovely Pents</b></p> <p>Who doesn't like a fantasy fox?</p>	<p><b>Oh, She Has 9 Arms</b></p> <ul style="list-style-type: none"> <li>How does she use them?</li> </ul>

**Background**

==ORIGIN==  
 <-insert tragic backstory here>

**Physical description**

Click [middlemouse](#) to drag page around  
 Press **Z** to zoom out!

**Final Illustration:** A full-body illustration of Oshichiya, a character with a pale, mask-like face, wearing a long, flowing red and blue kimono with intricate patterns. She has multiple arms (9 in total) holding various objects, including a fan and a sword. Her hair is black and styled in a traditional Japanese fashion with gold ornaments.

**Sketches:** A grid of 12 sketches showing different poses and outfits for Oshichiya, numbered 1 through 12.

## BEHAVIOUR

**In General**

The AI is executed through behaviour tree but in concept it is closely related to finite state machines. Each state has its own set of behaviour and moves closely together with the detection system in regards to sacrificing it between them.

I'll describe each state on a high level first and then further down you'll find visualisation for each of the individual tasks.

**RESEARCH**

Behaviour Systems


Default	Suppositions	Investigate	Asserted
<p>During the case the <i>Default</i> will return the <i>hypothesis</i> of the case in search of the player. If the player does not want the objective area and if it surrounds points of interest, it will return the <i>hypothesis</i> of the case.</p>	<p>When the AI has heard something and visibility to its origin isn't blocked (the AI will go to the suspicious place). The AI will turn and look towards the previous origin of the stimuli. After receiving a new stimulus, the player goes or back into the default state if it doesn't see the player.</p> <p>The AI does its own game like a "soft" response to the player. This means that if the player is seen and walks away, the AI's game will follow the player and not just stare with an empty gaze to the stimuli's origin.</p>	<p>The investigate state is triggered by the AI catching enough of a glance of the player or by the player's own stimuli. This state is used to investigate the player's location. In the investigate state the AI will move towards the player's origin to get closer to one location where the player could be. The player can move to a corner or place. This is completely based on it's own senses and logic.</p> <p>The player doesn't know where the player is beforehand.</p> <p>If the AI doesn't find the player it will proceed in the default state.</p>	<p>When alerted the AI will always be fully aware of the player's location and "start" in the state of "investigate". When located at the player's head, the player can see the player's eyes designed.</p> <p>When the player is in order to catch the player, after a while it will back off into the default state. The player can go to play the scenario as breaths again.</p>

**Default**

The default state is the initial and primary state for the AI. It's behaviour is to roam around and 'search' for the player. This is broken down in several sub-branches.

### Direct Move To

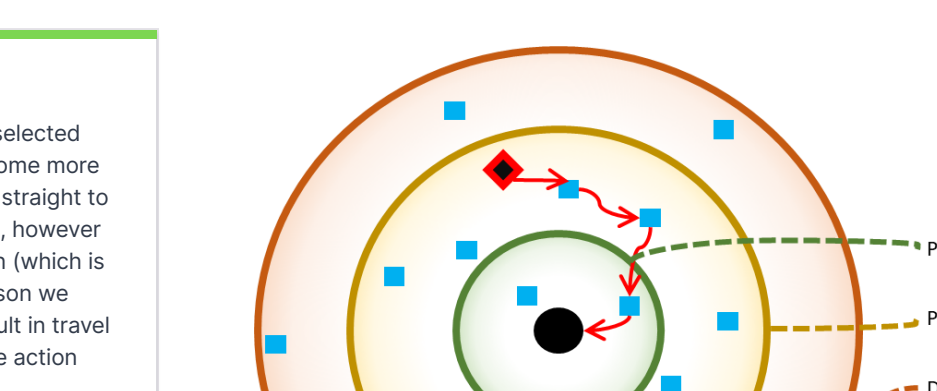
The basic most movement action where the AI directly run towards its target location. The action is preserved for only long distances. As it's not the most interesting action we only use it when we need to get AI from A to B in a reasonable time-frame.



- Obstacle
- Target Location
- Point of Interest

### Patrol Move To

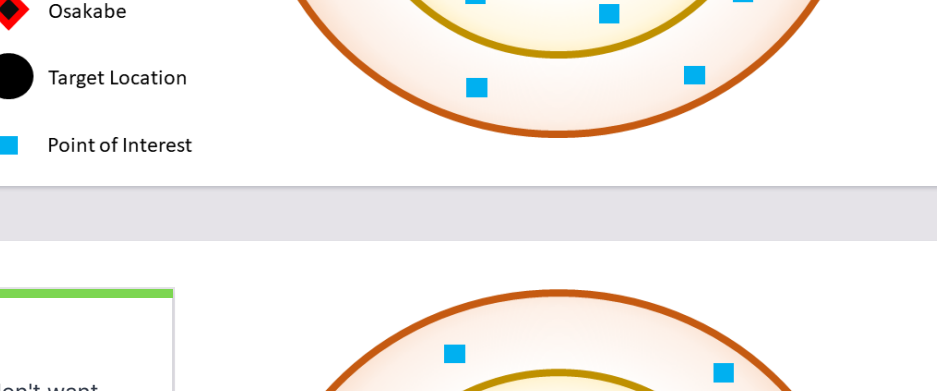
In this task the AI walks from A to B through a selected number of 'points of interest' which results in some more interesting behavior as the AI doesn't just walk straight to its targets. This is our preferred way of moving. However it is quite a bit slower due to the inefficient path (switch is on purpose to make it interesting). For that reason we don't use it for longer distances as it would result in travel times being too long and the information that the action was picked on isn't relevant anymore.



- Obstacle
- Target Location
- Point of Interest

### Patrol Area

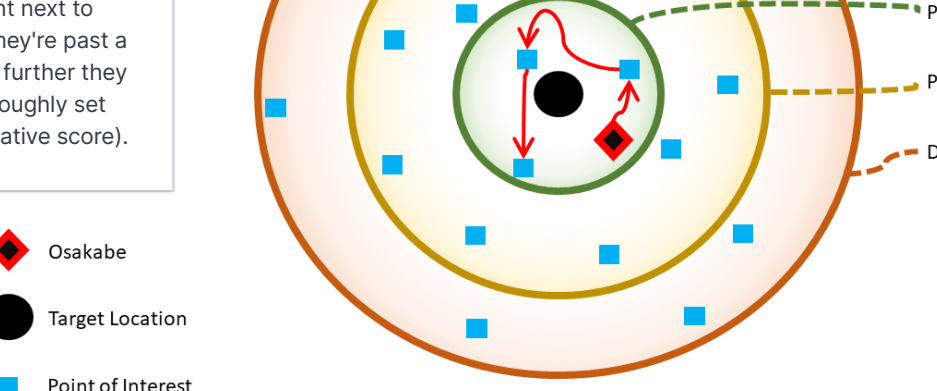
When the AI is already at their destination we don't want them to just stand there. In this case we activate 'point of interest' in the area it patrol through. It scores them on distance from each other (move to 3 points right next to each other wouldn't be too interesting) and if they're past a certain threshold they will score negatively the further they are removed from the target (this threshold is roughly set, so points in the same room won't receive a negative score).



- Obstacle
- Target Location
- Point of Interest

### Look At

If a destination is reached we don't want the AI to immediately move on, we want to emphasize that moment a little bit. (both as feedback but also as a window of time for the player to act while the AI doesn't move). We do this simply by making the AI scan the room for a bit. We can some tests based on where it can see the most (as it doesn't stare at a wall and then rotate the AI to look in that direction for a while until we proceed with its following action).



- Obstacle
- Look At Tests
- Winning Direction

**Suspicious**

This state is the AI's response to mild impulses. This can be a glance of the player or a noise from a visible location. Entering this state will cause the AI to look over to the location of the event that instigated it.

**Look**

This task will stop the AI in its track and will make it look over at the suspicious event. This is set to a timer value. If nothing is seen to fully alert it in that time it will proceed with its 'default' state behaviour.

[illegible]

**Alert**

At this point the AI is fully aware of the player. This is a brief moment of intense, pants shitting gameplay.

**Dashing**

The AI will dash at incredible speeds (almost jump-scare the player to a location nearby the player and right in the center of their view. Which then forms the 'Assault' dynamic together with the knowledge that looking at the AI deals the player damage.

Legend:

- Oskabe (Red Diamond)
- Player (Blue Circle)
- Visibility & Centre of View Scoring (Yellow Circle with 10)

**Background**

We use the background area to give the player some space to breath. This area is inaccessible to the player, meaning that is the AI is in it, it isn't an immediate threat to the player.

Secondly we use this to as a means for the AI to not meet without using actual turnoff reposition. When in the background the AI can sprint in a shortcut, meaning they're able to get anywhere faster then the player yet it still takes time (making it fair and easier for the player to anticipate because there are more defined rules to it).

**Entering Background**

The gateways between the foreground and the background. When the AI is told to move to the background it will move to a spot behind the entrance that it has the shortest walking distance. This is important as an entrance a floor higher may be close by but it is a longer walking distance. As well as one way entrances (such as a ledge that can be jumped down from but not up). It may be the easiest but if the AI can't jump up there it still has to walk around and find another way.

This task will abort all others as it's backing off, meaning it will ignore the player while it's running away.

Obstacle  
Entrance


**(In the Win) Movement**

Once in the background the AI will move to the entrance that's closest to its target location. If at all possible it will do so without ever leaving the background area. If the specific entrance is inaccessible that way it will travel through the foreground. To make clear the AI is in its background state it turn yellow but instead shows a smoky particle effect as feedback of it's movement to the player.

Obstacle  
Target  
Entrance

[illegible]

**RESEARCH**

 **Detection System**

As this is at such a short range the distance modifier itself will be a lot lower as well as the overall detection rate being a lot lower. This is a really just there to be able to see a player sprinting by at full speed.

To ensure a fair experience this view cone will not actually depict the player. Instead it will become 'suspicious' and the perception would have to be confirmed by one of the other sight senses. This way the AI has to look at the player before detecting them. This makes it very clear to the player when they're being seen.

**Focus**

This sight sense as to be activated upon which it will enable itself and disable the other sight senses.

With focus vision it's detection rate will be a lot faster as it was triggered by a noise for example.

Its cone is slightly shorter than the default but a lot tighter, to mimic tunnel vision. At though this is a threat at first glance it can also be used to the player's advantage by creating a distraction that will make the AI focus on that allowing the player a window to sneak by.

**Key:** BBSI - default; GREEN - parigorn; YELLOW - focus;

### What To Expect Here

The movement for a large part is based on systems in the Unreal Engine. We make use of objects such as the New-Mass and the Character Movement Component as the foundation of the AI's movement. Although we also use it for pathfinding, our application is slightly different. However, in here we describe the movement itself, how this is used by the AI can be seen in the more interesting "behaviour" section.

The main things covered here will be the components added to the existing Unreal systems. You can expect 'hubs' and the 'Background' level layer in the main topics.

### High-Level Description

The AI can move around the world as separate 'gates'. For this we use a 'hubs' system to update variables in runtime according to predetermined values. This means the AI never updates just one value (such as increase mass speed) but updates all values in the 'hubs' (so running isn't just an increase in speed but also acceleration and rotation rates).

Secondly we make use of a 'background' layer. This is a space in the level only the AI can enter. We use this to control the pace, either by moving the AI there to give the player some space to breathe or to give the AI a short-cut to get anywhere in the level faster (without just teleporting it).

### RESEARCH

### CAUTION!

Some aspect of movement systems in Unreal that normally can be left to assumption are slightly different here. Example are having multiple nav-meshes and using obstacle areas as data for other systems. Please read the technical documentation to be sure you're clear on how some systems are used differently then one might expect.

Movement Design Sketch, (Note that actions actions such as Barge and Crawl aren't part of the 'env')

BASIC MOVEMENT			
<p><b>'Rulebooks'</b></p> <p>The Oscalake has four basic movement options. These are: walk, run, sprint and dash. These are set in routine by using the 'Update Rulesbook' macro and selecting the desired 'gait' on its input pin. These 'Rulebooks' are a set of data-only blueprints that store values of a strict set of rules. These values are then sent by the AI as an 'event'. This makes it easier to consistently change these in runtime as it will set all the variables and objects need to set each variables manually.</p>	<p><b>Walk</b></p> <p>This 'gait' is used by the AI when there isn't much time for its actions. Typically, using the walk gait looks like Patrol Move To and Patrol Area.</p> <p>It is not particularly fast but will search through the area and doesn't have a need to speed up.</p> <p>The state also comes with slower acceleration and slower rotation rate and has no applied tracking force. This means it will eventually slow down as it approaches its destination.</p>	<p><b>Run</b></p> <p>The run is typically used in moments where we need to get to the AI's awareness before the moment has passed. This can be running towards something to investigate as well as the AI to search there before the player had plenty of time to get away. As well as when the movement destination is longer. If the AI would walk, by the time it reached the target it is nowhere near where it actually needs to be. Thus we run.</p> <p>Compared to walking, all variables are slightly scaled except for the tracking force. This remains to be not applied.</p>	<p><b>Sprint</b></p> <p>This 'gait' is unusually fast. It's only used in cases of the AI not being seen by the player. This can be for example when it's in the background of the player's view. It will ensure they're farther, even if the distance is longer.</p> <p>As not all background areas are connected it can occur that the AI has to pass through the open space to get there. In this case the AI is invisible and only noticed by smoke-trails appearing passing by. Inside this is defined by the behavior, this is not bound to this 'gait'.</p> <p>As this 'gait' isn't seen by the player a lot of 'invisibility' settings can be removed. Instant acceleration, rotation rate and brake force are used here, in combination with a high max speed.</p>
	<p><b>Dash</b></p> <p>The dash is exclusively used during the alert state to get to the player's view. It's pretty much a jump state that is just one step down from sprint tripping.</p> <p>The reason in this fast is because it needs to compete with the player's rotation rate. If the player looks away, the AI needs to get in center view just after.</p> <p>As the distances are often short the AI doesn't use any acceleration. If it did it would never reach the desired velocity. The same goes with rotation, at those speeds it doesn't make sense for to have any kind of turning circles, so it doesn't.</p>		
'BACKGROUND' MOVEMENT			

The diagram illustrates a game level layout with five distinct colored rectangular areas, each with a title and a description of its function and movement rules. Arrows indicate movement paths and relationships between these areas.

- Background** (Blue): We use the background area to give the player some space to breathe. This area is inaccessible to the player, meaning that the AI can't, it can't even immediately threat to the player. Secondly we use this as a means for the AI to find threat without using actual (unfair) teleportation. When in the background the AI can sprint in a direction, making it very easy to get anywhere faster than the player will still allow them to sprint (making it fair and even for the player to anticipate because there are more defined routes to it).
- Areas** (Orange): The background layer isn't level marked with the gameplay and the background will be accurately placed but what is important is that the entire background area is overlapped and none of the gameplay is. They only purpose is to be used in checks to see where the AI is. This information is then used in the behavior tree.
- Entrances** (Green): The 'entrances' are the gateways between the gameplay and the background. These have a front face and a background face. They come with a New-link to connect the ramennames. These are set up for regular movement in a floor but a level designer can move the new-link into the instance to use it as a for vertical movement like jumping down. In those cases it's also need to specify that the entrance can only be used in those specific direction. To make the AI aware it can jump down but not up.
- Navigation** (Purple): Every passage between the two layers are marked with 'navlink' new areas. Using a custom new link "OokskadeBaf" when can use that to identify point to a different level layer as the AI. The cost of the obstacle is set to 10000, meaning we can use it to identify areas when we aware that every <10000 in the same layer as the AI. The new link name "nulloccatort" can be filter out all the passages which would force the AI to move while walking in the level layer is in. Please view the technical documentation for a more detailed view on the specific uses of the navigation system.